



Overview of Feasibility Studies on CE-5: Free Maneuvering

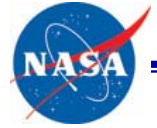
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DAG-TM Workshop

15 November 2002



Outline of Presentation

- Background
- Summary of selected studies
 - Properties of air traffic conflicts for free and structured routing
 - Performance evaluation of airborne separation assurance for Free Flight
 - System performance characteristics of centralized and decentralized air traffic separation strategies
 - Stability of intersecting aircraft streams with self-separation
 - Aircraft conflict resolution with an arrival time constraint
 - Agent-based approach to constrained conflict resolution
- Lessons learned
- Open research issues



Background

- Initial feasibility evaluation of Free Maneuvering operations
 - Focus on high-level performance characteristics and issues
 - Perfect information
 - No human in the loop
- Key issue: Effects of decentralized separation assurance
 - Can separation be maintained under decentralized rules?
 - What are the effects on system efficiency?
 - What are the implications for system stability (domino effect)?
 - What is the impact on conformance to local-TFM constraints?
- Numerous studies conducted (FY00 – FY02)
 - In-house work at Ames
 - RTO-36 and RTO-67 (Seagull)
 - Cooperative Agreements with MIT



Relevant Publications (1 of 2)

1. Bilimoria, K.D. and Lee, H.Q., "Aircraft Conflict Resolution with an Arrival Time Constraint," Paper No. 2002-4444, *AIAA Guidance, Navigation, and Control Conference*, August 2002.
2. Mueller, K.T., Schleicher, D., and Bilimoria, K.D., "Conflict Detection and Resolution with Traffic Flow Constraints," Paper No. 2002-4445, *AIAA Guidance, Navigation, and Control Conference*, August 2002.
3. Dugail, D., Feron, E., and Bilimoria, K.D., "Conflict-Free Conformance to En Route Flow-Rate Constraints," Paper No. 2002-5013, *AIAA Guidance, Navigation, and Control Conference*, August 2002.
4. Harper, K.A., Guarino, S.L., Hanson, M.L., Bilimoria, K.D., and Mulfinger, D.G., "An Agent-Based Approach to Aircraft Conflict Resolution with Spatial Constraints," Paper No. 2002-4552, *AIAA Guidance, Navigation, and Control Conference*, August 2002.
5. Dugail, D., Feron, E., and Bilimoria, K., "Stability of Intersecting Aircraft Flows using Heading Change Maneuvers for Conflict Avoidance," Paper INV-5005, *American Control Conference*, May 2002.
6. Krozel, J., Peters, M., Bilimoria, K.D., Lee, C., and Mitchell, J.S.B., "System Performance Characteristics of Centralized and Decentralized Air Traffic Separation Strategies," *4th USA/Europe Air Traffic Management Research and Development Seminar*, December 2001; also, *Air Traffic Control Quarterly*, Vol. 9, No. 4, December 2001, pp. 311–332.



Relevant Publications (2 of 2)

7. Bilimoria, K.D. and Lee, H.Q., “Properties of Air Traffic Conflicts for Free and Structured Routing,” Paper No. 2001-4051, *AIAA Guidance, Navigation, and Control Conference*, August 2001.
8. Mao, Z.-H., Feron, E., and Bilimoria, K., “Stability and Performance of Intersecting Aircraft Flows under Decentralized Conflict Avoidance Rules,” Paper No. 2000-4271, *AIAA Guidance, Navigation, and Control Conference*, August 2000; also, *IEEE Transactions on Intelligent Transportation Systems*, Vol. 2, No. 2, June 2001, pp. 101–109.
9. Bilimoria, K.D., “A Geometric Optimization Approach to Aircraft Conflict Resolution,” Paper No. 2000-4265, *AIAA Guidance, Navigation, and Control Conference*, August 2000.
10. Bilimoria, K.D., Sheth, K.S., Lee, H.Q., and Grabbe, S.R., “Performance Evaluation of Airborne Separation Assurance for Free Flight,” Paper No. 2000-4269, *AIAA Guidance, Navigation, and Control Conference*, August 2000; also, *Air Traffic Control Quarterly*, to appear.
11. Bilimoria, K.D., Lee, H.Q., Mao, Z.-H., and Feron, E., “Comparison of Centralized and Decentralized Conflict Resolution Strategies for Multiple-Aircraft Problems,” Paper No. 2000-4268, *AIAA Guidance, Navigation, and Control Conference*, August 2000.

Papers available upon request



Study #1

Properties of Air Traffic Conflicts for Free and Structured Routing

» **Karl Bilimoria and Hilda Lee**
Paper No. 2001-4051
AIAA Guidance, Navigation, and Control Conference
Montréal, CANADA
August 2001



Problem Definition

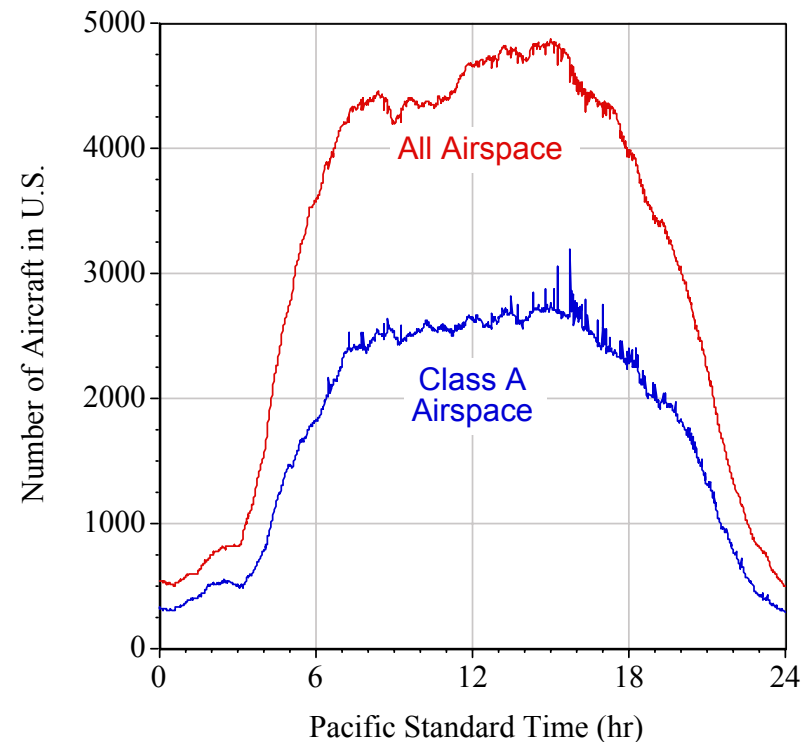
- Research Questions:
 - How often would conflicts occur in the absence of corrective action?
 - What are the key properties of conflicts?
 - What is the level of interaction between individual conflicts?
 - Does free routing significantly change the number/nature of conflicts?
- Approach
 - Conduct simulation based on real traffic data from current operations
 - » Aircraft-to-aircraft conflicts only
 - » Wind effects not modeled
 - Study conflicts only in Class A airspace (at or above FL180)
 - » Trajectories in lower airspace can vary significantly from flight plans
 - » Significant percentage of flights in lower airspace are VFR flights



Conflict Data Collection

- Enhanced Traffic Management System (ETMS) data for a 24-hr period in March 2001
 - 57,402 aircraft total
 - 37,926 aircraft in Class A airspace
- Birth points and times captured from ETMS data
- Aircraft fly to destination in 3-D simulation, with Conflict Resolution **OFF**
 - Free (great circle) routing
 - Structured (flight plan) routing

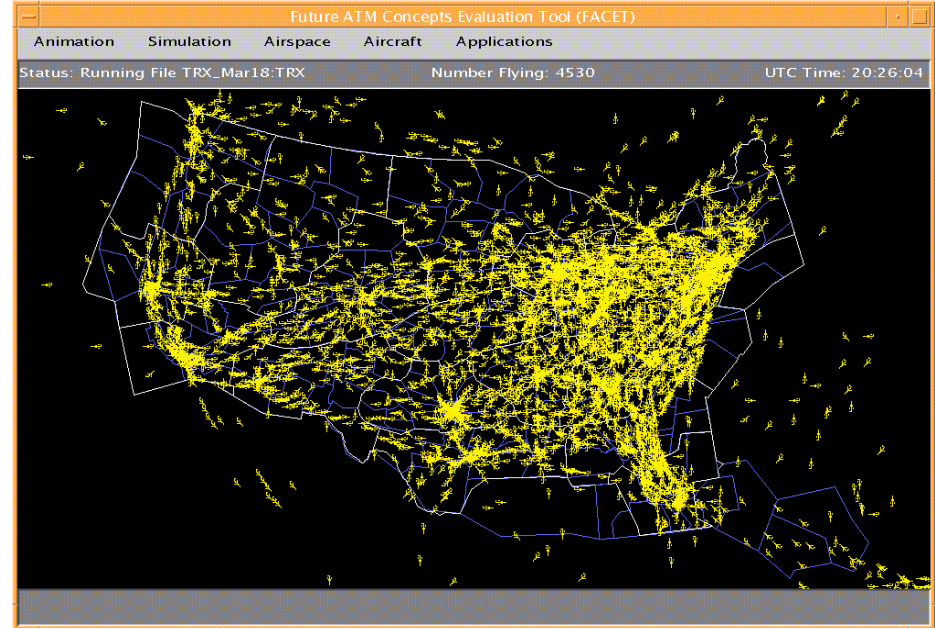
Aircraft Count vs. Time





FACET: Future ATM Concepts Evaluation Tool

- Simulation tool for exploring advanced ATM concepts
 - Developed at NASA-Ames
- Airspace Modeling (over contiguous U.S.)
 - Center/sector boundaries
 - Jet/Victor airways
 - Navigation aids
 - Airports
- Trajectory Modeling
 - Fly flight-plan routes or direct (great circle) routes over round earth
 - Climb/descent performance models
 - Dynamic models for turns and acceleration/deceleration

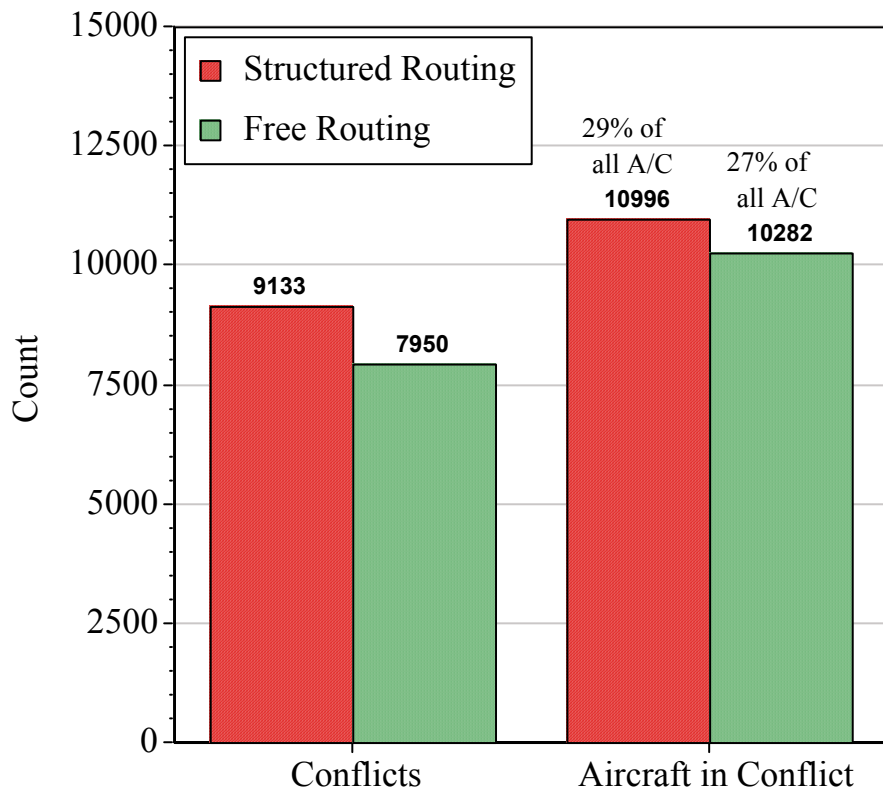


Bilimoria, K.D., Sridhar, B., Chatterji, G.B., Sheth, K.S., and Grabbe, S.R., “FACET: Future ATM Concepts Evaluation Tool,” *Air Traffic Control Quarterly*, Vol. 9, No. 1, 2001, pp. 1–20.

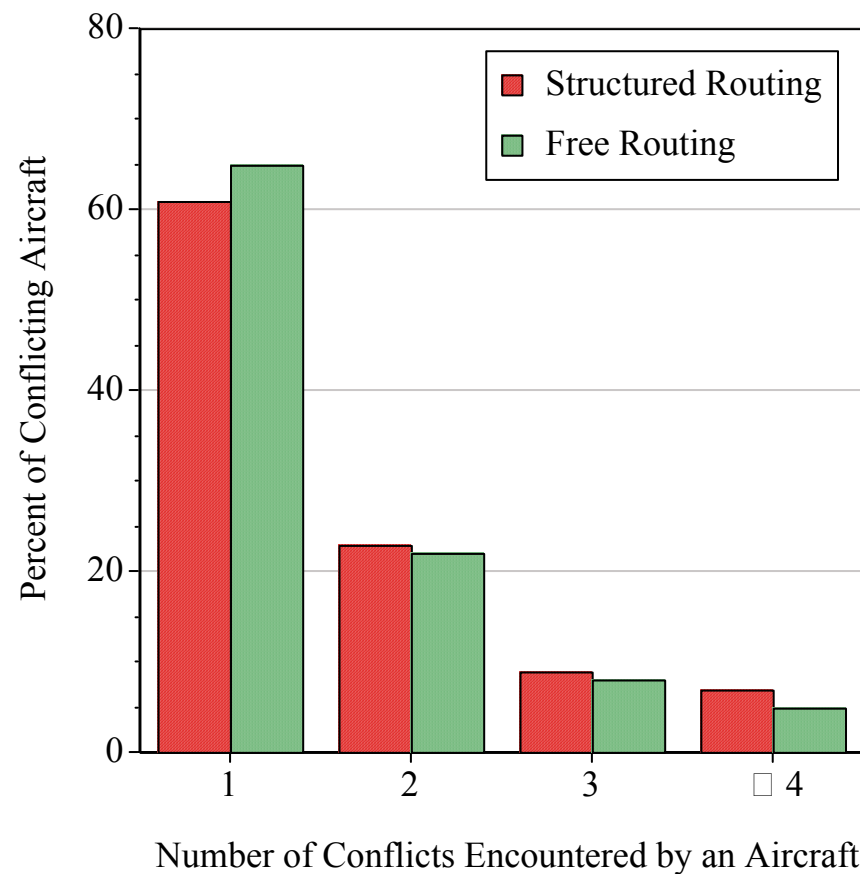


Results: Number of Conflicts

Counts of Conflicts and Aircraft



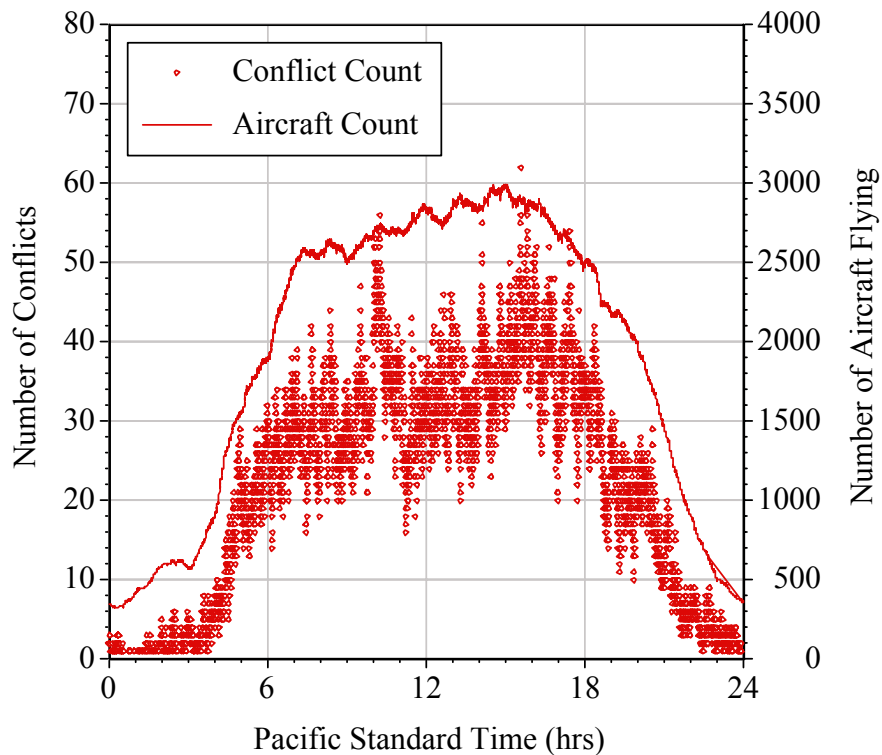
Number of Conflicts per Aircraft



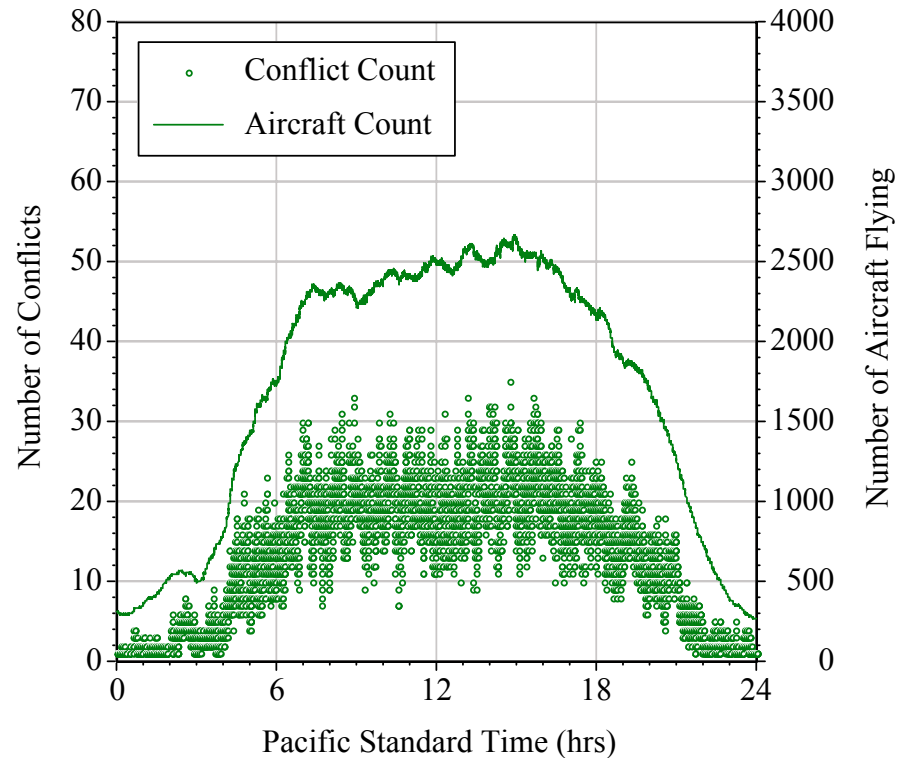


Results: Conflict Counts vs. Time

Structured Routing



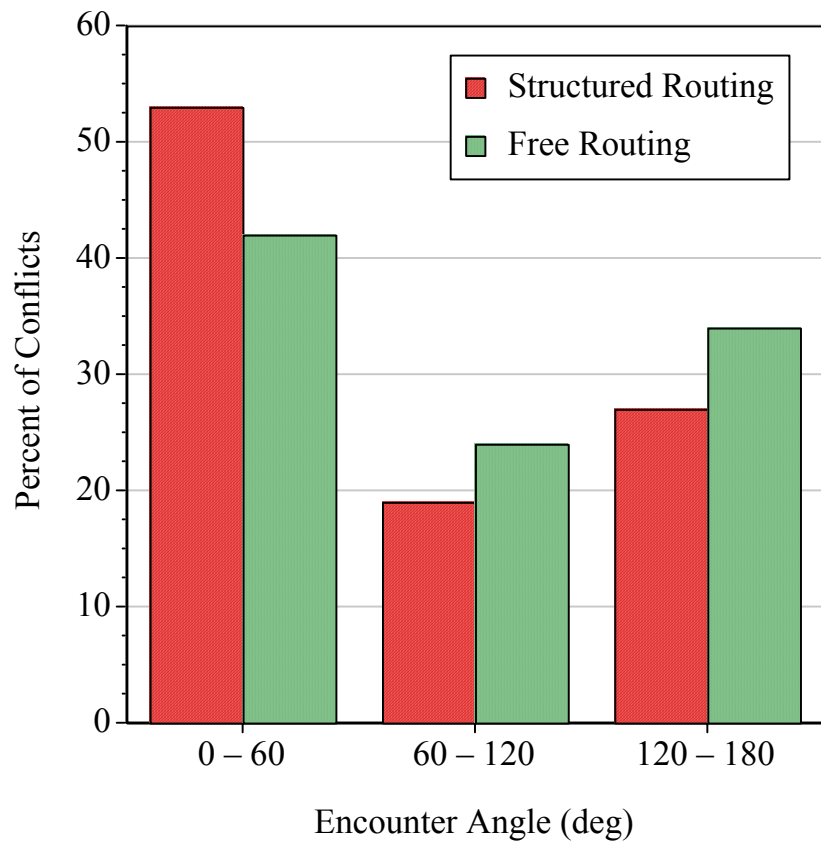
Free Routing



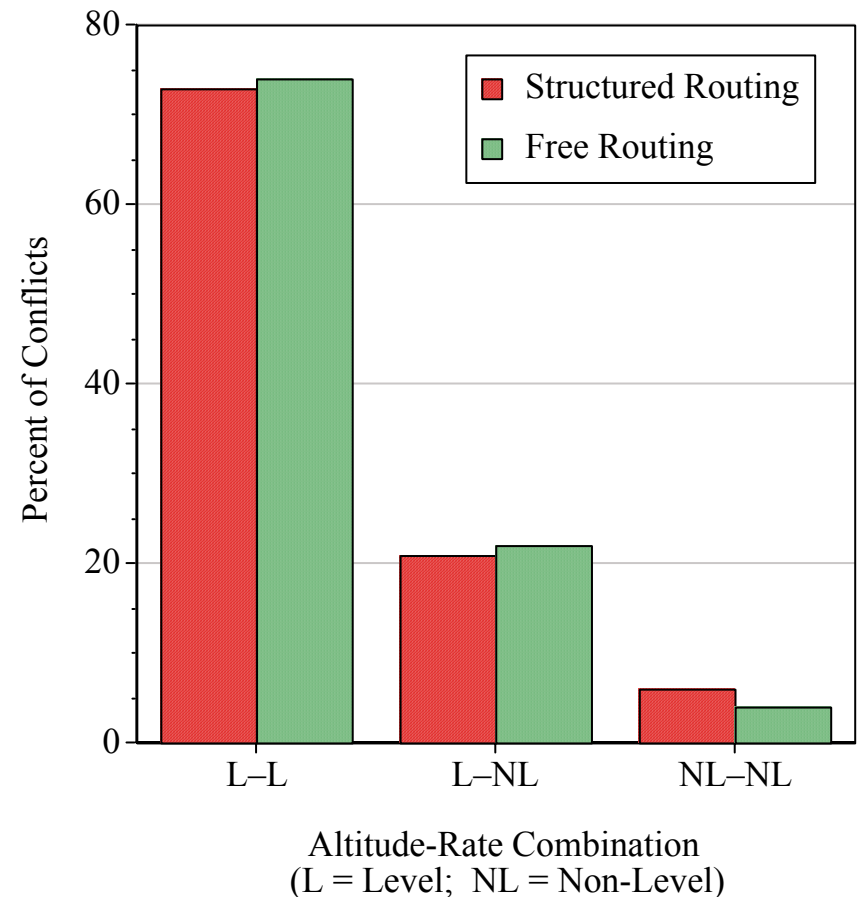


Results: Conflict Properties

Encounter Angle Distributions

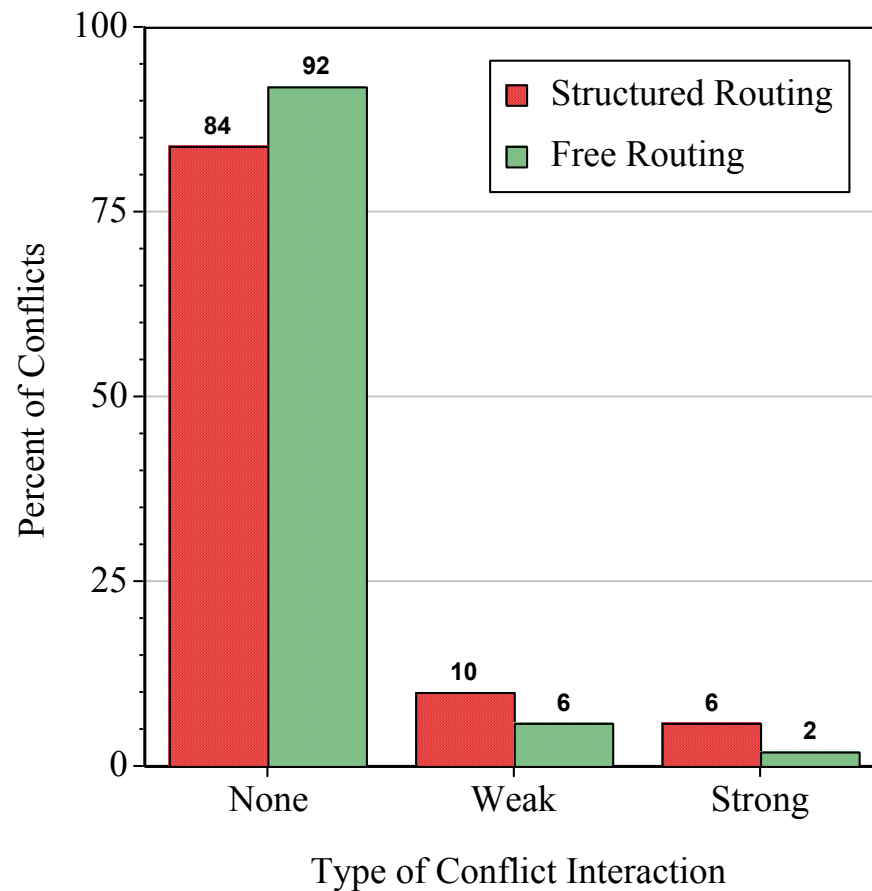
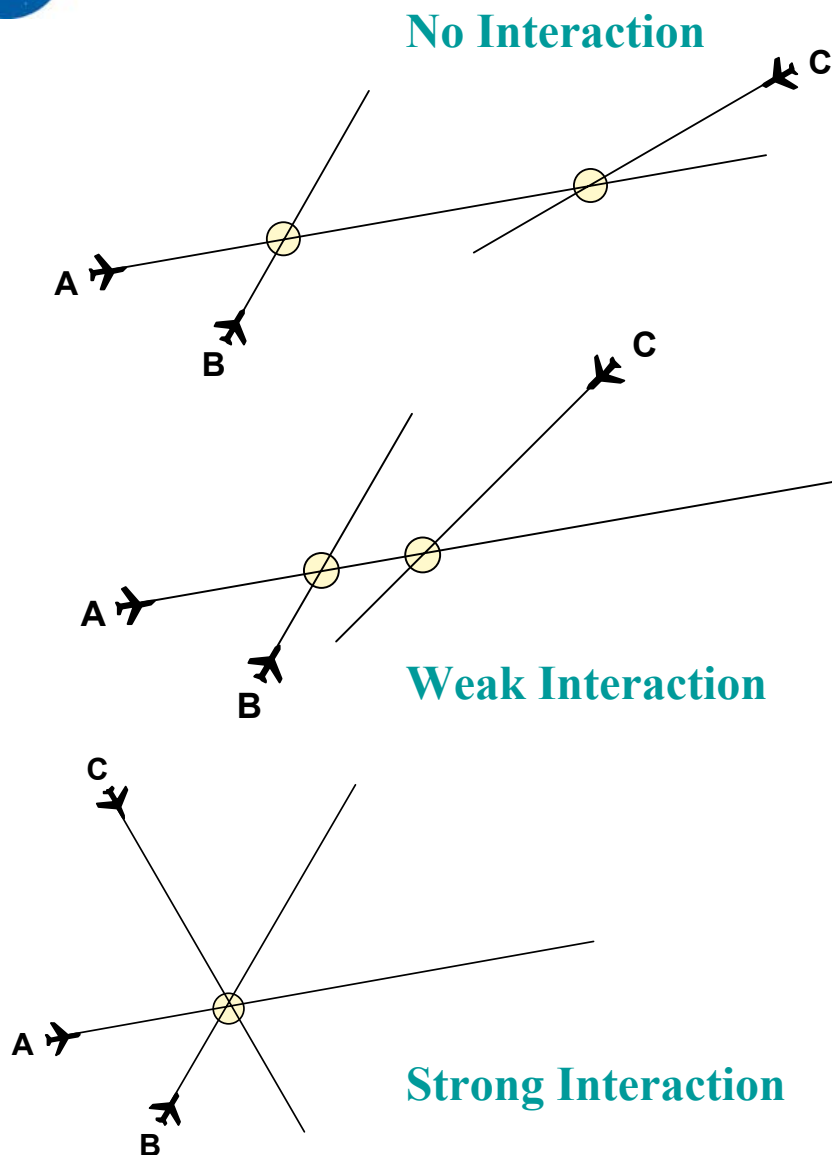


Altitude-Rate Distributions





Results: Conflict Interactions





Summary of Study #1

- Investigated conflict properties for free and structured routing in a simulation based on 24 hours of real traffic data (ETMS)
 - Results for conflicts in Class A airspace
- Less than 30% of aircraft ever experienced a conflict
 - Of these, about 40% experienced more than one conflict
- About 75% of conflicts involve only level-flying aircraft
- Most (~85%) conflicts had no significant interaction
 - Useful information for design of conflict resolution tools
- Free routing has ~10% fewer conflicts than structured routing
 - Supports feasibility of Free Flight concept



Study #2

Performance Evaluation of Airborne Separation Assurance for Free Flight

» **Karl Bilimoria, Kapil Sheth, Hilda Lee, and Shon Grabbe**
Paper No. 2000-4269
AIAA Guidance, Navigation, and Control Conference
Denver, CO
August 2000



Problem Definition

- Research Objectives:
 - Study feasibility of airborne separation assurance for free flight
 - Develop techniques to assess performance of CD&R algorithms

- Approach
 - Use two qualitatively different CD&R methods
 - » Geometric Optimization approach
 - » Modified Potential-Field approach
 - Create a realistic Free Flight traffic scenario
 - » Utilize initial conditions obtained from real traffic data
 - Evaluate system performance using metrics
 - » Safety
 - » Efficiency
 - » Stability



Free Flight Traffic Scenario

- Birth points extracted from Enhanced Traffic Management System (ETMS) data
 - 3 hours of data for Denver Center, from 9 am – 12 noon, on 18 March 1999
 - 955 aircraft in Class A airspace (\geq FL180)
- Free Flight simulation
 - Fly direct route from birth point to destination (great circle navigation)
 - Deviate from nominal trajectory as necessary for conflict resolution
 - Conflict resolutions shared equally
 - Horizontal flight only
 - » Each aircraft flies at its cruise (maximum) altitude found in ETMS tracks



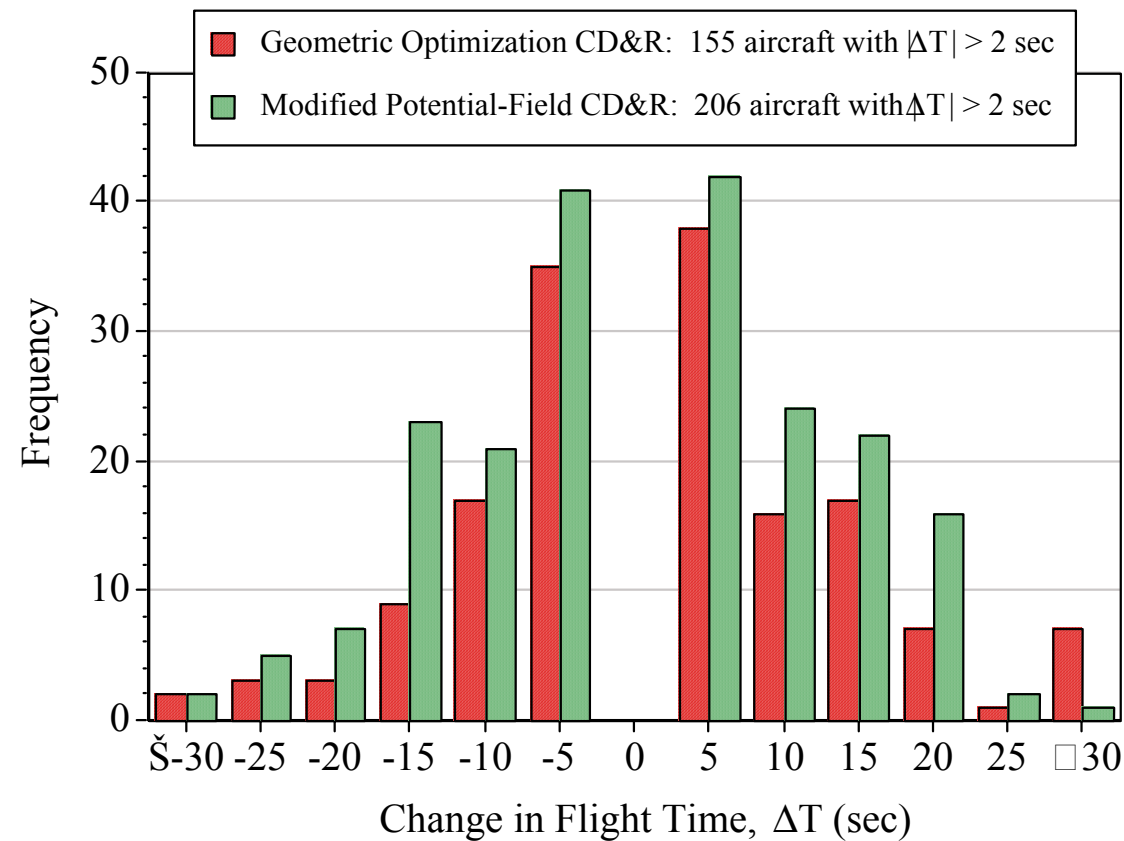


Metrics for Performance Evaluation

- Safety
 - Number of observed conflicts (loss of separation) with CD&R engaged
- Efficiency
 - Incremental cost of conflict resolution, measured by:
 - » Change in path length (relative to nominal trajectory with no CD&R)
 - » Change in flight time (relative to nominal trajectory with no CD&R)
- Stability
 - Conflict resolution often creates new conflicts – “domino effect”
 - » Number of deviated aircraft that were not nominally in conflict
 - » Number of aircraft, nominally in conflict, that were not deviated



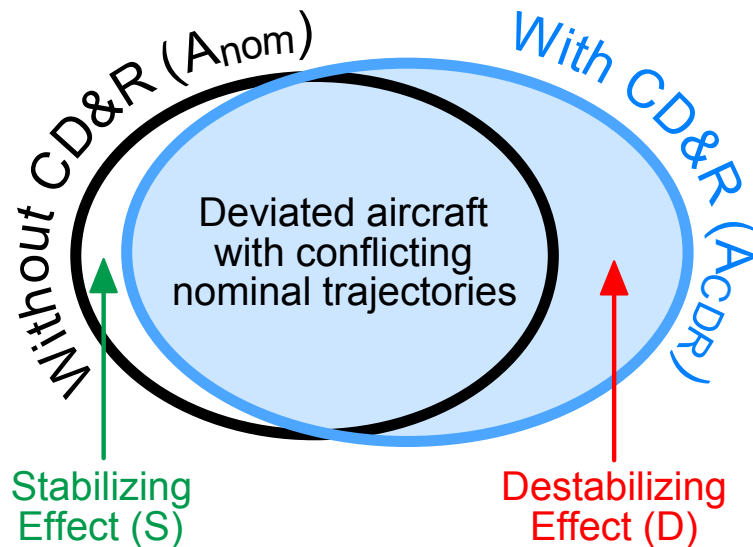
Efficiency Results: Flight-Time Changes



	Geometric Optimization CD&R Method	Modified Potential-Field CD&R Method
Count for $ \Delta T $	155 aircraft	206 aircraft
Sgn. Mean	6 sec	2 sec
Abs. Mean	12 sec	11 sec
Abs. Sum	1810 sec	2226 sec



Stability Results



Domino Effect Parameter

$$DEP = \left[\left(\frac{D}{A_{nom}} \right) - \left(\frac{S}{A_{nom}} \right) \right] = \left(\frac{D - S}{A_{nom}} \right)$$

	Geometric Optimization CD&R Method	Modified Potential-Field CD&R Method
A_{nom}	209	209
A_{CDR}	248	352
D	47	145
S	8	2
DEP	0.19	0.68



Summary of Study #2

- Investigated feasibility of self-separation using a Free Flight traffic scenario constructed from real air traffic data
- All conflicts were resolved
- Deviations of individual trajectories were very small
 - Mean flight-time changes ~ 10 sec
 - Mean path-length changes ~ 1 nm
- Impact on system stability is dependent on CR method
 - Percentage of additional aircraft drawn into conflicts $\sim 20\%$ to 70%
- These preliminary results support the feasibility of airborne separation assurance for Free Flight



Study #3

System Performance Characteristics of Centralized and Decentralized Air Traffic Separation Strategies

» **Jimmy Krozel, Mark Peters, Karl Bilimoria, Changkil Lee, and Joseph Mitchell**
» **4th USA/Europe Air Traffic Management R&D Seminar**
» **Santa Fe, NM**
» **December 2001**



Problem Definition

- Research Questions:
 - Does decentralized CD&R create a domino effect? How strong is it?
 - What does the domino effect do to system-wide trajectory deviations?
 - How does system performance vary with traffic density?
- Approach
 - Simple implementations of two types of separation strategies
 - » Centralized: Emphasizes system stability – tries to suppress domino effect
 - » Decentralized: Emphasizes efficient resolution of individual conflicts
 - ☎ Myopic: Focuses exclusively on aircraft-level efficiency
 - ☎ Look-ahead: Gives up some efficiency to gain some stability
 - Run Monte Carlo simulations of free flight, using randomized traffic scenarios
 - » Simulate varying traffic densities (up to $\sim 5\times$ current peak en route density)
 - Measure domino effect, and determine its impact on trajectory deviations



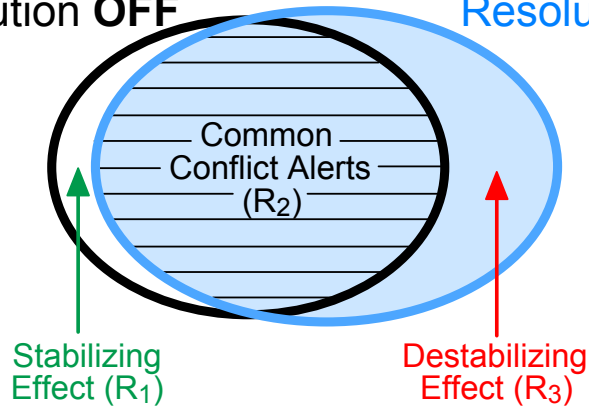
- Run time of 50 minutes for each scenario
- 16 traffic densities
- 18 randomized traffic scenarios at each density (total 288 scenarios)
- Each scenario was run with:
 - Conflict Resolution (CR) off
 - Centralized CR
 - Myopic Decentr. CR
 - Look-ahead Decentr. CR



Domino Effect Parameter vs. Traffic Density

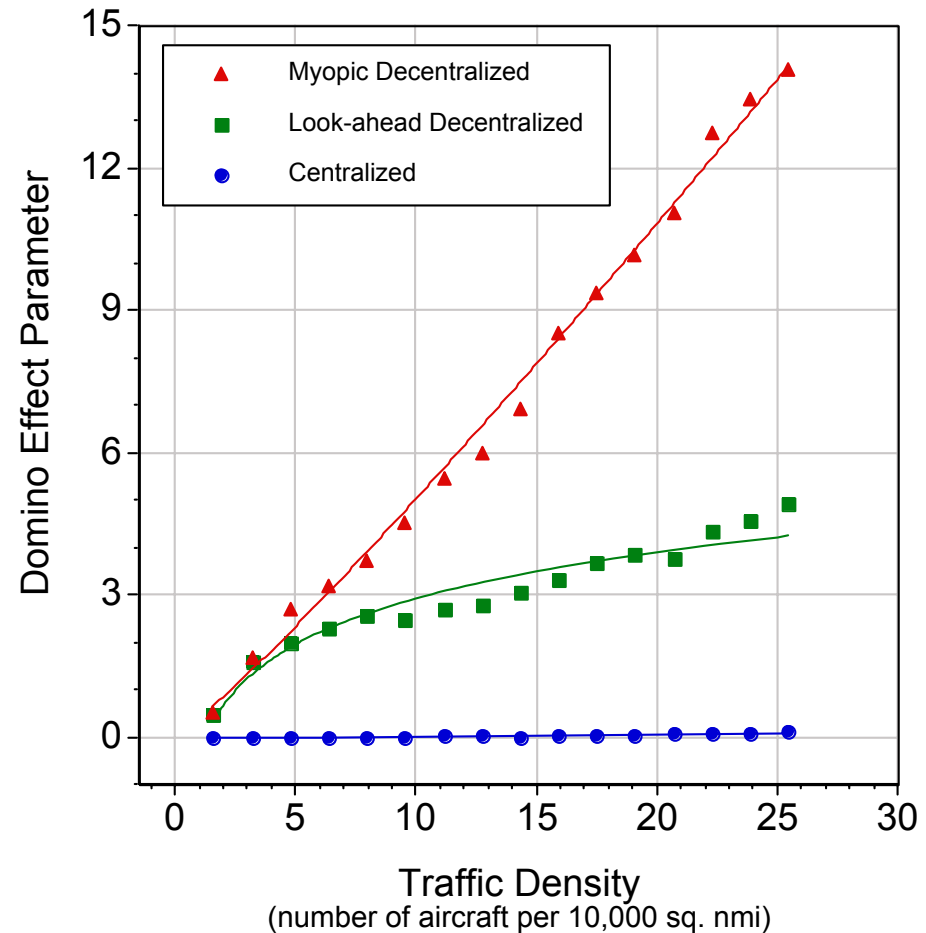
S₁: Conflict Alerts with Resolution **OFF**

S₂: Conflict Alerts with Resolution **ON**



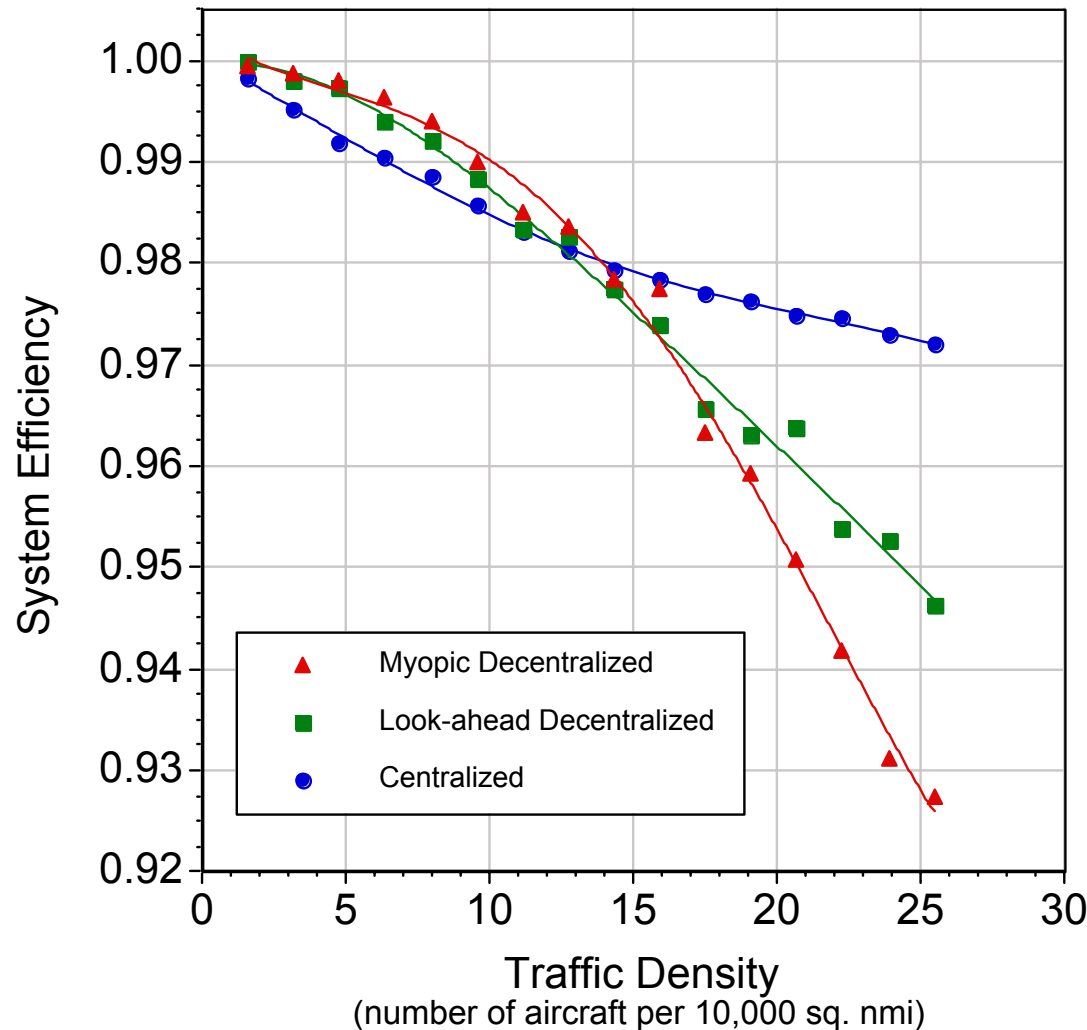
Domino Effect Parameter

$$DEP = \left(\frac{|R_3| - |R_1|}{|S_1|} \right) = \left(\frac{|S_2|}{|S_1|} - 1 \right)$$





System Efficiency vs. Traffic Density



$$E_{sys} = \frac{1}{N} \sum_{i=1}^N \left(1 - \frac{\Delta l_i}{l_i} \right)$$

- Even a 1% change in system efficiency is significant from an operational perspective
- Crossover between Centralized and Decentralized strategies at about 13 a/c per 10^4 sq. nmi
- Crossover between the Myopic and Look-ahead Decentralized strategies at about 16 a/c per 10^4 sq. nmi



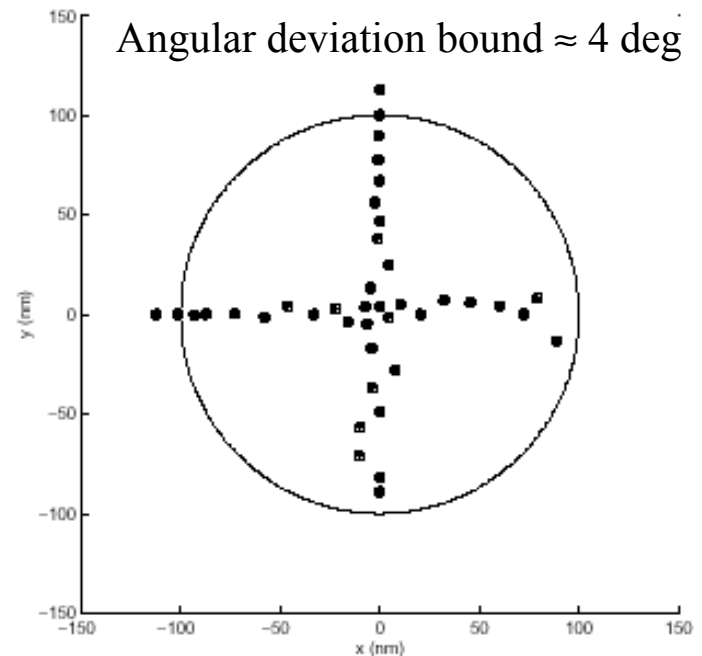
Summary of Study #3

- Investigated impact of domino effect on system performance
- System efficiency degrades with increasing traffic density for centralized as well as decentralized separation strategies
- Decentralized separation strategies can create a strong domino effect, especially at very high traffic densities. However,
 - Domino effect does not significantly degrade system efficiency up to a threshold traffic density
 - Threshold density can be increased by adding a look-ahead feature
- Mitigation of domino effect should be an important factor in the design of algorithms for airborne separation systems



Study #4: Stability of Intersecting Streams

- **Objective:** Determine stability characteristics of intersecting streams of aircraft operating under decentralized CD&R rules (self-separation)
 - Developed an analytical proof for stability, and checked it via simulations
- Stability defined as existence of bounds on trajectory deviations
- Determined analytical expression for bounds on trajectory deviations to resolve “streaming” conflicts
- Bound values cross-checked by numerical simulations
 - Excellent agreement



Mao, Z.-H., Feron, E., and Bilimoria, K.D., “Stability and Performance of Intersecting Aircraft Flows under Decentralized Conflict Avoidance Rules,” *IEEE Transactions on Intelligent Transportation Systems*, Vol. 2, No. 2, June 2001; and, Dugail, D., Feron, E., and Bilimoria, K.D., “Stability of Intersecting Aircraft Flows using Heading Change Maneuvers for Conflict Avoidance,” Paper INV-5005, *American Control Conference*, May 2002



Study #5

Aircraft Conflict Resolution with an Arrival Time Constraint

» **Karl Bilimoria and Hilda Lee**

•Paper No. 2002-4444

AIAA Guidance, Navigation, and Control Conference

Monterey, CA

August 2002



Problem Definition

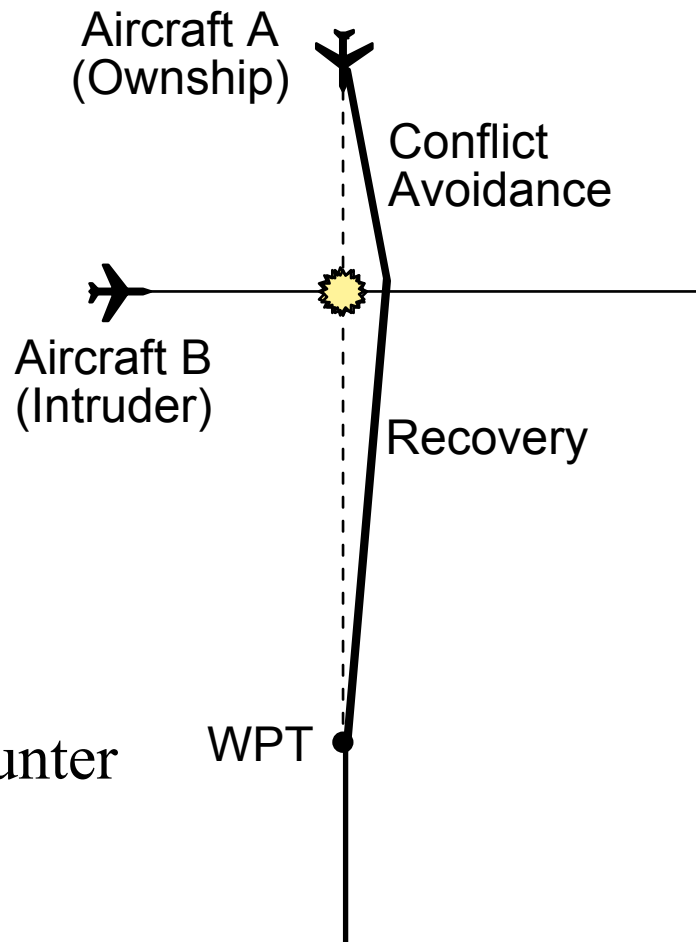
- Research Objectives:
 - Investigate structure of conflict resolution families with RTA constraints
 - Determine effects of aircraft performance limits on existence of solutions

- Approach
 - Extend the Geometric Optimization method to handle RTA constraints
 - » Avoidance solutions: Heading change, Speed change, Optimal (hdg + spd) change
 - » Recovery solution: Change heading to capture WPT; adjust speed to meet RTA
 - Delay Compensated avoidance solution
 - » Avoids conflict using a special combination of heading and speed
 - » Delay caused by path stretching is exactly compensated by speed increase
 - » Recovery speed equals nominal speed
 - Use simple model of aircraft performance (speed and acceleration) limits
 - Conduct parametric study to reveal structure of solutions for conflict resolution with RTA constraint



Parametric Study

- Fundamental parameter for RTA study is $\tau = (t_{FLS} / t_{RTA})$ where $t_{RTA} = (l_{WPT} / V_{NOM})$
- Determined family of CR solutions for 7 values of l_{WPT} :
55, 60, 75, 100, 150, 200, 250 nm
- Computed solution families for 3 encounter angles: 30, 90, 150 degrees
- Avoidance: Heading, Speed, Optimal change; Delay Comp.





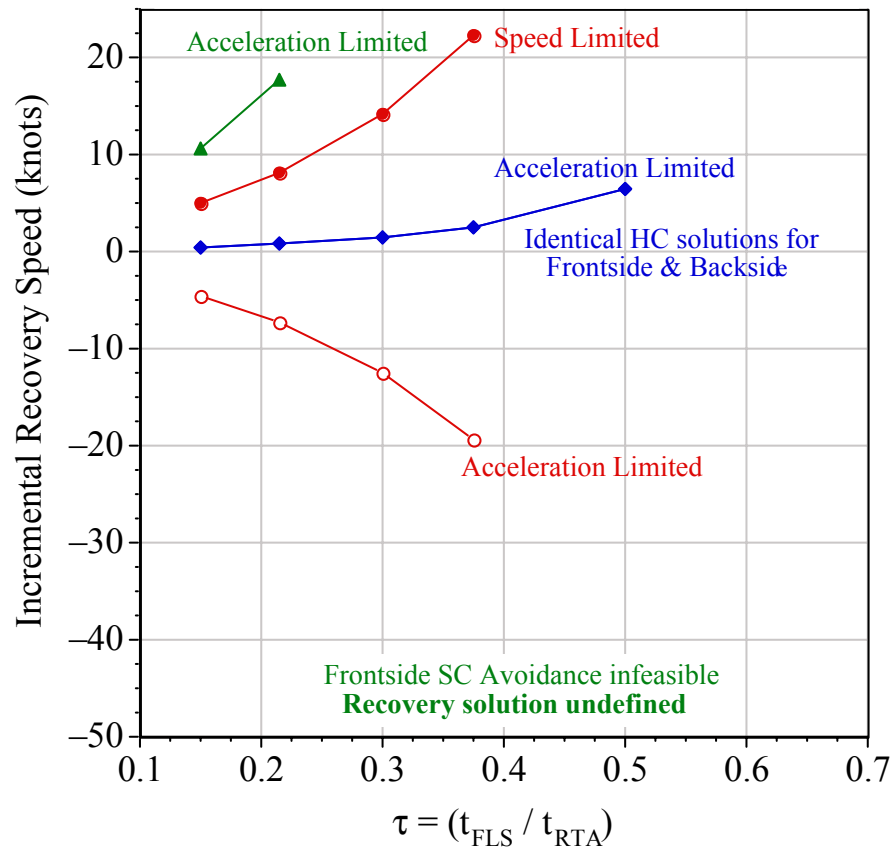
Parametric Study: 90 deg Encounter

Backside Avoidance

- Heading Change
- Optimal Change
- Speed Change

Frontside Avoidance

- Heading Change
- Optimal Change

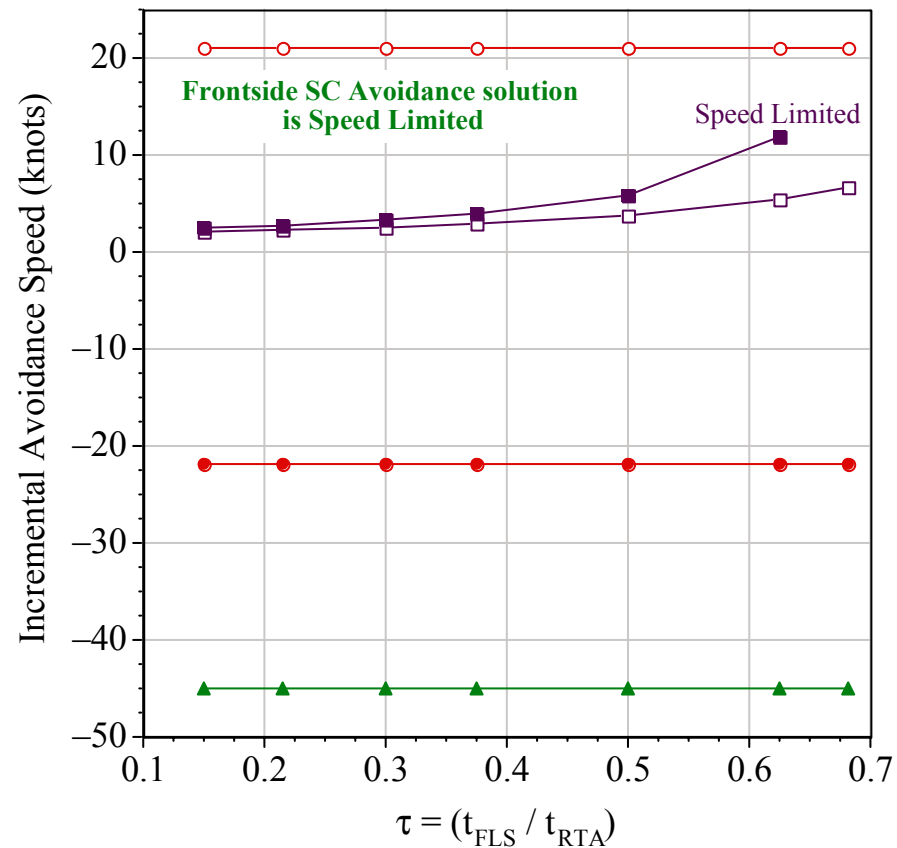


Backside Avoidance

- Optimal Change
- Speed Change
- Delay Compensated

Frontside Avoidance

- Optimal Change
- Delay Compensated





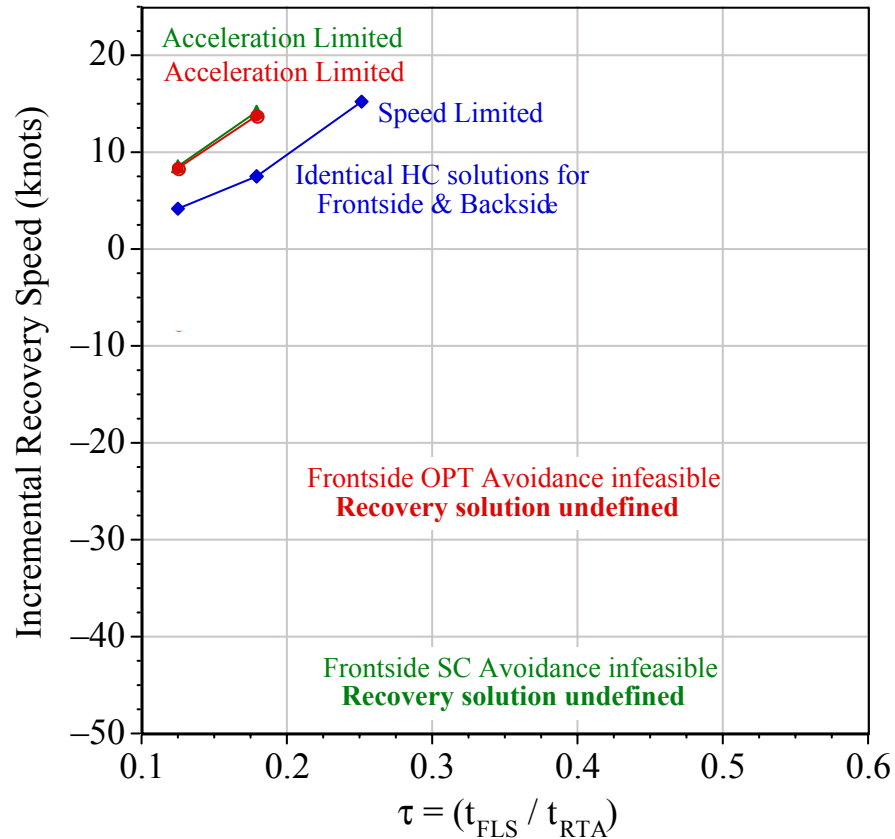
Parametric Study: 30 deg Encounter

Backside Avoidance

Frontside Avoidance

- Heading Change
- Optimal Change
- Speed Change

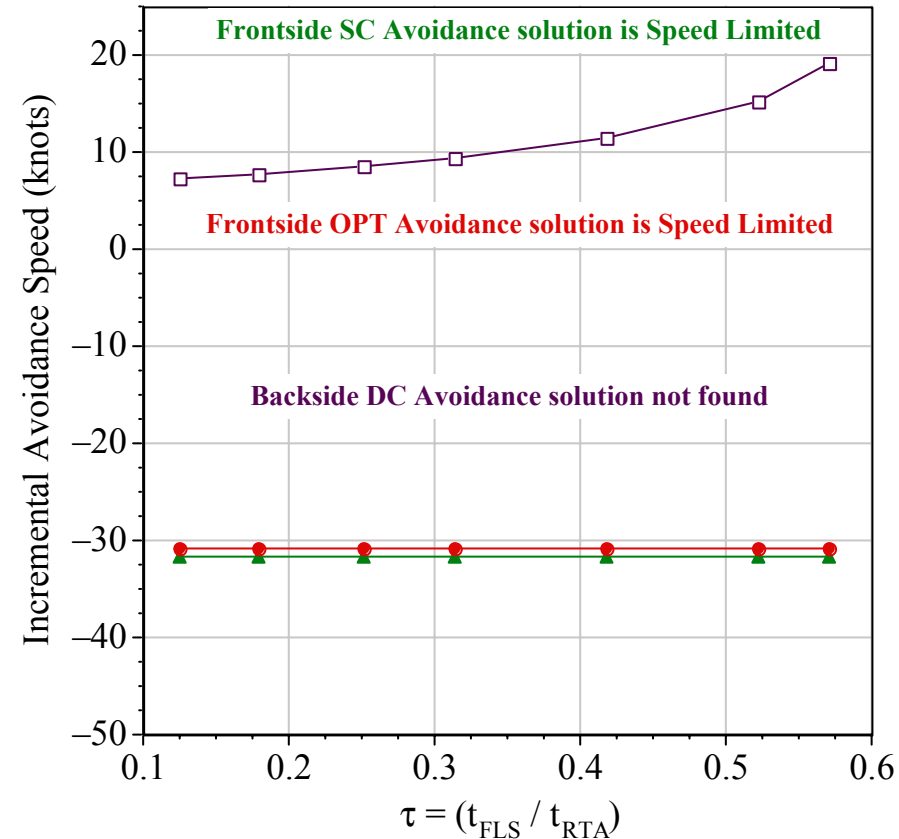
- Heading Change



Backside Avoidance

Frontside Avoidance

- Optimal Change
- Speed Change
- Delay Compensated





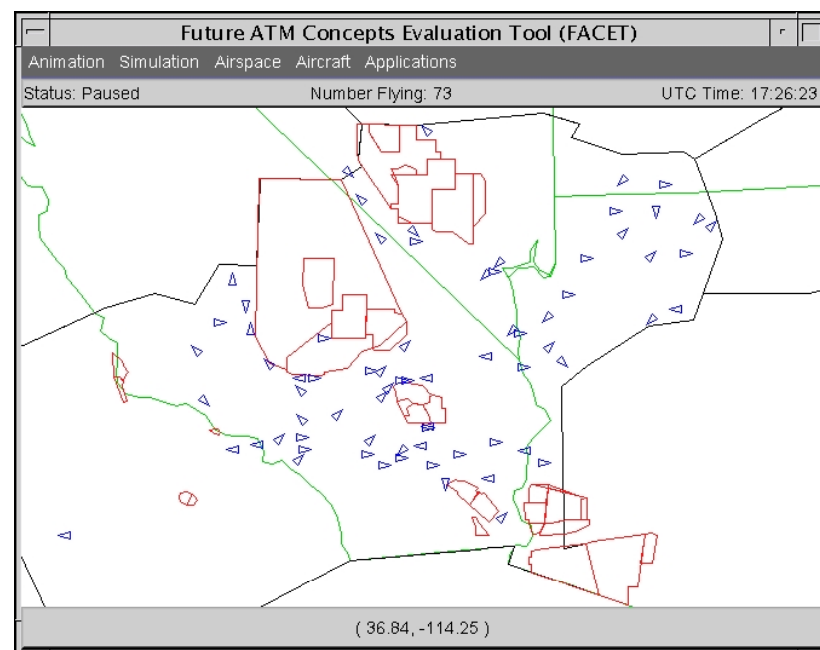
Summary of Study #5

- Generated families of conflict avoidance and recovery solutions, characterized by severity of arrival time (RTA) constraint
- The domain of feasible resolutions is constrained by aircraft performance (speed/acceleration) limits
 - Delay Compensated solution has larger domain of feasibility
 - Other operational solutions could be determined by numerical search
- Required speed often exceeds performance limits if the time to conflict is more than half of the required time to next waypoint
- Prioritization rules for conflict resolution should favor the aircraft that is closer to its RTA



Study #6: Agent-Based Conflict Resolution

- **Objective:** Develop agent-based approach to conflict resolution
- In DAG-TM operations, negotiated resolution of conflicts may be necessary in situations involving constraints: Wx cells, SUA, RTA, etc.
- Pilot and controller agents utilize Principled Negotiation approach
- Starting with a 50-50 split, agents negotiate an equitable solution that satisfies all constraints
- FACET study, using realistic traffic and SUA data for LA Center, shows about 10% of conflicts need negotiation



Harper, K.A., Guarino, S.L., Hanson, M.L., Bilimoria, K.D., and Mulfinger, D.G., "An Agent-Based Approach to Aircraft Conflict Resolution with Spatial Constraints," Paper No. 2002-4552, *AIAA Guidance, Navigation and Control Conference*, August 2002.



Constraint Hierarchy

1. Aircraft maneuver constraints
 - Hard constraints that are impossible to violate
2. Separation constraints
 - Strong constraints that are possible to violate (if extreme conditions warrant doing so), but must generally be respected for safety reasons
3. Flow management constraints
 - Constraints that generally do not have a significant impact on safety, if violated on an individual flight basis
 - Violation of these constraints may have a negative effect on the flow of traffic and result in reduced flight efficiency
4. User preference constraints
 - Soft constraints that generally do not reduce safety when exceeded
 - There is a cost to the aircraft operator, either directly in terms of dollars or indirectly in terms of passenger dissatisfaction, if these constraints are significantly exceeded



Lessons Learned (1 of 2)

- Conflicts can be resolved without central coordination
 - Resolved conflicts for traffic scenarios created from real (ETMS) data
 - Resolved multiple-aircraft “converging” conflicts; decentralized solutions showed only ~10% degradation relative to benchmark centralized solutions
 - Derived analytic proof of stable resolutions for “streaming” conflicts
- Trajectory deviations for conflict resolution (distance or time) are very small compared to nominal trajectory length or time
 - Differences in efficiency between various algorithms likely to be quite small
 - Differences in stability could be significant
- Domino effect is not a “show stopper”
 - Trajectory deviations small at current density, even for “myopic” resolutions
 - Significant degradation of efficiency at high (e.g., 3x) densities, but...
 - Degradation can be significantly attenuated by imposing the following rule:
Resolution of a conflict should not cause any new short-term conflicts



Lessons Learned (2 of 2)

- Conflict Resolution with TFM constraints
 - Required speed often exceeds aircraft performance limits if the time to conflict is more than half of the required time to next waypoint
 - Delay Compensated avoidance maneuver can alleviate this problem
 - Conflict resolution rules should assign priority to aircraft closer to RTA
 - Negotiated resolution can solve highly constrained conflicts
- In en route airspace, at current traffic density:
 - Free routing reduces the number and complexity of conflicts
 - Less than 30% of aircraft ever experienced a conflict
 - Horizontal plane conflicts represent about 75% of total conflicts
- Overall, the results from all studies support the feasibility of Free Maneuvering for user-preferred separation assurance and local-TFM conformance



Open Research Issues

- Cooperative or non-cooperative conflict resolution?
 - Non-cooperative resolution requires comprehensive and unambiguous flight rules to establish priority
 - » Can these rules be made to work for multiple-aircraft conflicts?
 - » Can these rules be extended to resolution with constraints (SUA, RTA, etc.)?
 - » Is non-cooperative resolution sufficient in highly constrained situations?
 - Cooperative resolution may require more complex procedures and/or algorithms
 - » Can it reduce domino effect at very high traffic densities?
 - » What type of implicit coordination is required?
 - » Is explicit coordination required for highly constrained conflicts?
- Must all “autonomous” aircraft use the same CD&R algorithm?
 - Significant issue for cooperative resolution
 - Less relevant for non-cooperative resolution

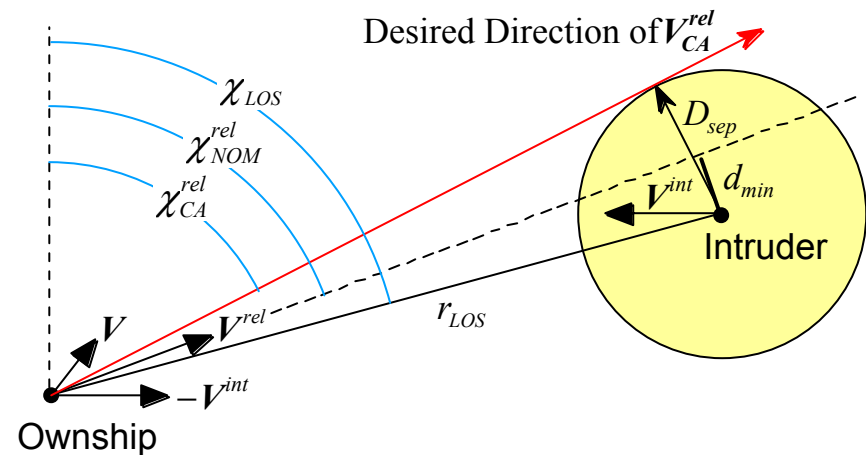


Backup Slides

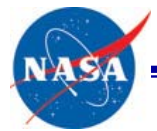


Geometric Optimization CR Algorithm (1 of 2)

- Developed an algorithm for efficient resolution of aircraft conflicts
 - Seeks to minimize deviations from nominal trajectory
 - Geometric characteristics of aircraft trajectories are utilized to determine closed-form analytical expressions for conflict avoidance commands
 - » Best heading-speed combination
 - » Heading
 - » Speed
 - » Altitude-rate
- Implemented algorithm in ATM simulation environment (FACET)
- Conducted extensive testing with very challenging scenarios



Bilimoria, K.D., "A Geometric Optimization Approach to Aircraft Conflict Resolution," Paper 2000-4265, *AIAA Guidance, Navigation, and Control Conference*, August 2000.



Geometric Optimization CR Algorithm (2 of 2)

- Formal mathematical verification of the Geometric Optimization CR algorithm conducted at LaRC as part of a safety assessment of DAG-TM
 - e.g., no faults in logic flow, no divisions by zero, always returns solution
- Extended G.O. algorithm for conflict resolution with RTA conformance
 - Determine recovery speed and course to meet RTA at next waypoint
 - Delay Compensated avoidance solution (combination of speed and heading)
- Geometric Optimization CR software may be used for upcoming DAG-TM piloted simulations to study Human Factors aspects of self-separation
- Self-separation studies conducted using Geometric Optimization CR
 - Performance of decentralized CD&R for complex multiple-aircraft problems
 - » Works for 8-aircraft problems (28 simultaneous conflicts)
 - » Performance degradation (relative to centralized CD&R) is around 10%
 - Feasibility of self-separation in simulated Free Flight with realistic traffic
 - » Conducted using FACET